

Adventures In Real-Time Performance Tuning, Part 2

The real-time for Linux patchset does not guarantee adequate real-time behavior for all target platforms. When using real-time Linux on a new platform you should expect to have to tune the kernel and drivers to provide performance that matches your specific requirements.

Part 1, presented at ELC 2008, provided an example of the trials and tribulations of the tuning journey for a MIPS target board.

Part 2 will provide additional examples of methods to debug and tune latency. An additional target for this installment is an SMP ARM board, leading to a new set of challenges.

Adventures In Real-Time Performance Tuning, Part 2

With thanks to the Sony SS kernel team in Tokyo for their contributions to this tuning and debugging process.

Overview

Background and Definitions

Some Tuning Strategies and Tactics

Examples of Tuning

Quick Summary of Part 1

Examples of using the old latency instrumentation from the RT patchset to tune latency

`/proc/latency_hist/interrupt_off_latency/CPU*`

`/proc/latency_trace`

The new, improved “ftrace” instrumentation appears in the RT patchset 2.6.24-rt2 and mainline 2.6.27-rc1

Quick Summary of Part 1

Characterization of the (large) overhead of latency instrumentation

Tuning a component of overall latency (micro-tuning) can have a negative impact on the overall latency

The value of data visualization (graphs) vs. basic statistics such as min, max, avg, std deviation.

What Is Different

part 1

Linux 2.6.24, MIPS target, UP

part 2

Linux 2.6.23, ARM target, SMP

What is Real Time?

It is determinism (being able to respond to a stimulus before a deadline) within a given system load envelope.

It is NOT fast response time.

The specific real time application deadlines determine how short the maximum response time must be to deliver real time behavior.

Some examples of deadlines are one second, one millisecond, or five microseconds.

RT latency is the delay from stimulus to when the RT “application” is executing code

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Possible RT application contexts include

- driver interrupt context
- driver thread context
- kernel thread context
- user space thread context

RT latency is the delay from stimulus to when the RT “application” is executing code

The components that add up to RT latency are important to the tuning process, but keep in mind the goal of tuning actual RT latency.

Some components that may contribute to RT latency

- IRQ disabled time
- preempt disabled time
- IRQ latency, from event until bottom half
- RT driver bottom half(s) execution
- non-RT driver bottom half(s) execution
- task switch time

Some components that may contribute to RT latency

- IRQ disabled time
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- task switch time

The components that add up to RT latency are important to the tuning process, but keep in mind the end goal of tuning actual RT latency.

Strategy: Compare Kernel Versions

Use Case #1

I'm stuck on kernel version 2.6.n, but there are reports on the linux-rt-users email list that performance on version 2.6.n + 3 is much better.

Is there some fix that I can port to my kernel version?

Strategy: Compare Kernel Versions

Use Case #2

I moved forward from kernel version 2.6.n to 2.6.n+1 and performance got worse.

Tactics

#1 Compare kernel config options

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#2 Compare the behavior and/or performance metrics

Raw Interrupt Latency

Latency of timer interrupt to interrupt bottom half execution.

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Problem: latency increased from 6 usec to 11 usec
on move from 2.6.22 to 2.6.23

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Latency of timer interrupt to interrupt bottom half execution.

Problem: latency increased from 6 usec to 11 usec on move from 2.6.22 to 2.6.23

Disclaimer: all kernel versions in this presentation are based on kernel.org, but with patches added, so these results may not be repeatable on kernel.org versions

Tactics

#1 Compare kernel config options

#2 Compare the behavior and/or performance metrics

Revert the config differences, starting with the most likely culprits.

Metric: raw interrupt latency.

Results

<u>option</u>	<u>value</u>	<u>usec</u>
NR_CPUS	4 -> 2	9/10 -> 9
NO_HZ	y -> n	9 -> 6
PREEMPT_RCU_BOOST	y -> n	6 -> 5
SLAB -> SLOB		5/6 -> 5
others		no big affect

Task Wake Up Time

Goal: average task wake up time < XXX usec

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Problem: actual task wake up time $>> XXX$ usec

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Goal: average task wake up time $< XXX$ usec

Problem: actual task wake up time $>> XXX$ usec

Observation:

2.6.22	avg: 23 usec	max: 33 usec
2.6.23	avg: 72 usec	max: 244 usec

Tactics

- #1 Compare kernel config options
- #2 Compare the behavior and/or performance metrics
- #3 Compare the source code
  - the real-time patch set
  - the base kernel
- #3b Read the current version of the source code

Task Wake Up Test (simplified)

```
/* producer kernel thread, SCHED_FIFO, priority = 98 */

pthread() {
    counter = 10000;

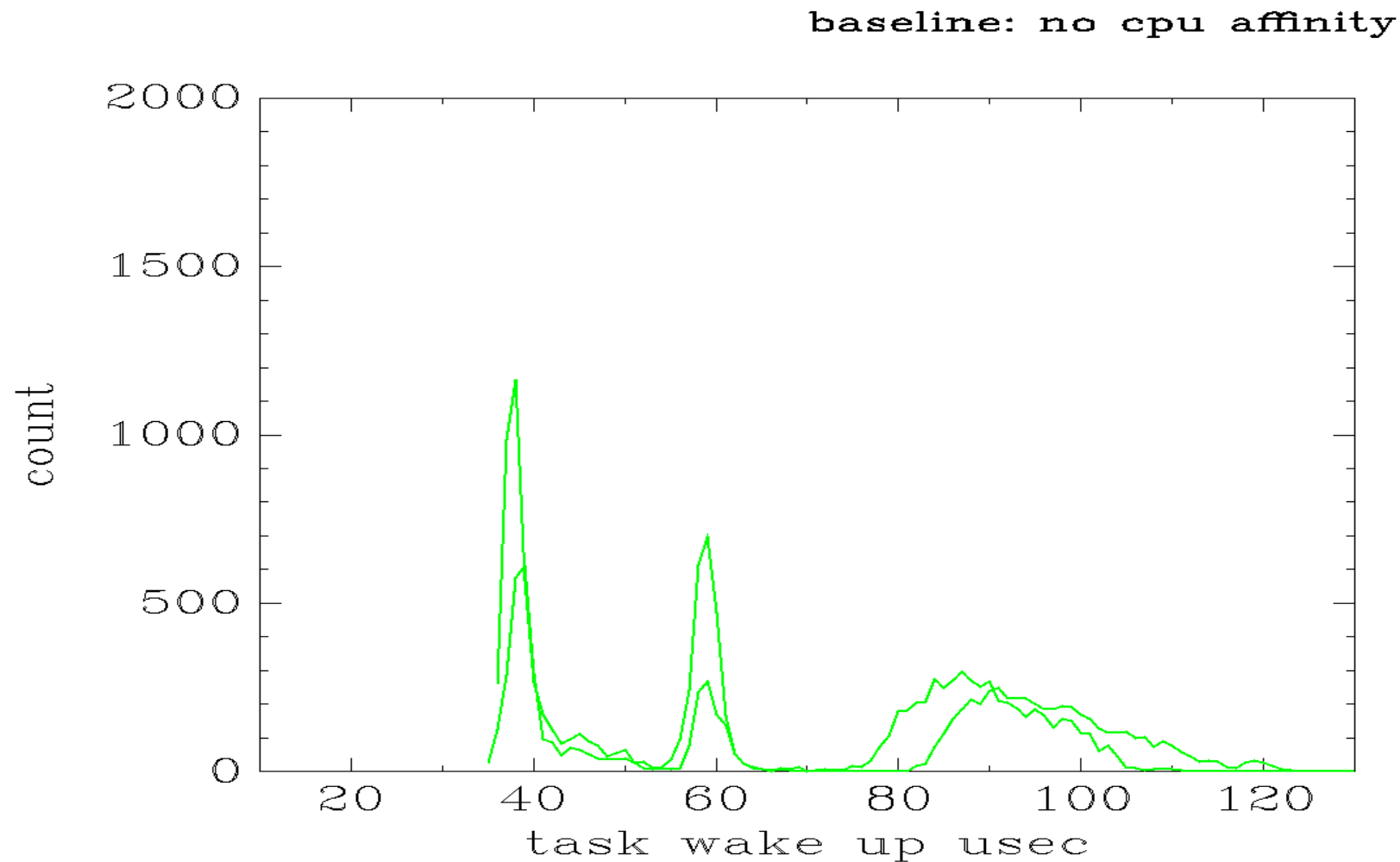
    while (counter-- > 0) {
        mbx->timestamp = read_time();
        set_current_state(TASK_UNINTERRUPTIBLE);
        wake_up_process(ctsk);
        schedule_timeout(DELAY);
    }

    done = 1;
    wake_up_process(ctsk);
}
```

Task Wake Up Test (simplified)

```
/* consumer kernel thread, SCHED_FIFO, priority = 99 */  
  
cthread() {  
  
    while (1) {  
        delta = read_time() - mbx->timestamp;  
        update_stats(delta);  
        set_current_state(TASK_UNINTERRUPTIBLE);  
        if (done)  
            break;  
        schedule();  
    }  
  
    report_stats();  
}
```

2.6.23 Task Wake Up Time



Intuitive Leap 1

Which processor is each thread on?

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Which processor is each thread on?

(Ignoring the strategy and tactics for a moment!)

Methodology (M1)

(M1) Instrument the test application

Add mbx->cpu

Producer sets to current cpu

Consumer compares to current cpu

Result (M1)

	--- producer ---	
consumer	cpu 0	cpu 1
-----	-----	-----
cpu 0	0	5000
cpu 1	4999	1

This may be good - each task is on its own processor.

Result (M1)

	--- producer ---	
consumer	cpu 0	cpu 1
-----	-----	-----
cpu 0	0	5000
cpu 1	4999	1

This may be good - each task is on its own processor.

Next Question:

How frequently did producer move between cpus?

Methodology (M2)

(M2) Instrument the test application some more

Log producer and consumer cpu for each iteration

Result (M2)

```
# producer cpu map:
```

#

[illegible]

#

```
# consumer cpu map:
```

#

[illegible]

Result (M2)

producer cpu map:

#

0 01010101010101010101010101010101010101010101010101010101

70 01010101010101010101010101010101010101010101010101010101

#

consumer cpu map:

#

0 10101010101010101010101010101010101010101010101010101010

70 10101010101010101010101010101010101010101010101010101010

Result (M2)

```
# producer cpu map:
```

```
#
```

```
#      0  0101010101010101010101010101010101010101010101010101
```

```
#      70 0101010101010101010101010101010101010101010101010101
```

```
#
```

```
# consumer cpu map:
```

```
#
```

```
#      0  1010101010101010101010101010101010101010101010101010
```

```
#      70 1010101010101010101010101010101010101010101010101010
```

Excessive migration is usually not good.

Compare to 2.6.22

	---	producer	---
consumer	cpu 0		cpu 1
-----	-----		-----
cpu 0		10000	0

(Returning to the strategy and tactics.)

Compare to 2.6.22

```
# producer cpu map:
```

#

```
#      0  00000000000000000000000000000000000000000000000000000
```

```
# 70 000000000000000000000000000000000000000000000000000
```

#

```
# consumer cpu map:
```

#

```
#      0  00000000000000000000000000000000000000000000000000000
```

```
# 70 00000000000000000000000000000000000000000000000000000
```

Fix (F1)

Set processor affinity for pthread() and cthread()

Fix (F1)

Set processor affinity for `cthread()` and `pthread()`

Goal: verify that task migration is the cause of the increased task wake up time.

Fix Result (F1)

producer cpu affinity	consumer cpu affinity	task avg	switch max	usec
-----	-----	-----	-----	
x	x	69	147	baseline
x	x	68	159	baseline

Fix Result (F1)

producer cpu affinity	consumer cpu affinity	task avg	switch max	usec
-----	-----	-----	-----	
x	x	69	147	baseline
x	x	68	159	baseline

Each line is a 10000 iteration test run result.

This data does not match the original problem statement (avg 72, max 244) due to changes in kernel configuration.

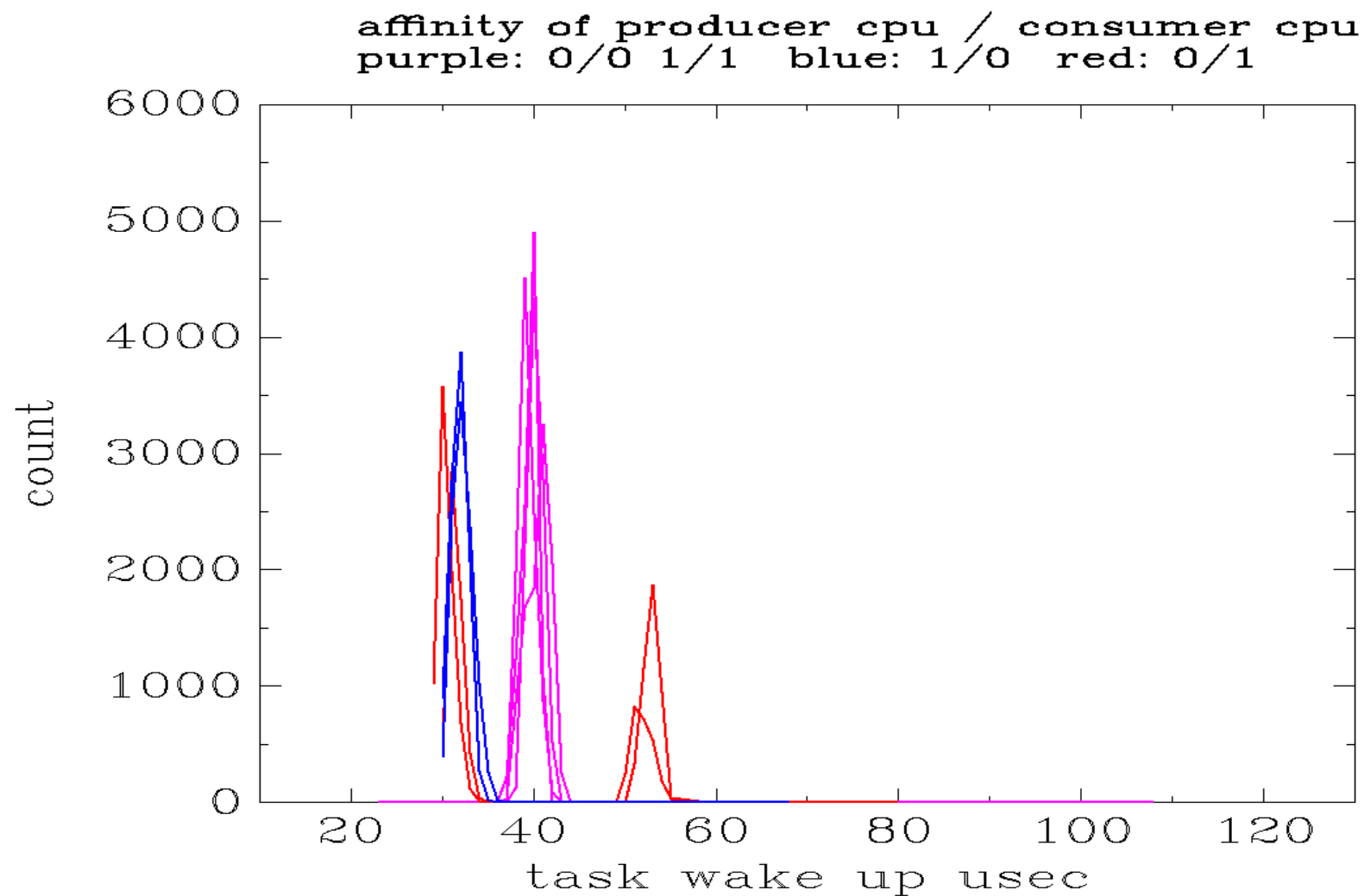
Fix Result (F1)

producer cpu affinity	consumer cpu affinity	task avg	switch max	usec
-----	-----	-----	-----	
x	x	69	147	baseline
x	x	68	159	baseline
0	0	39	64	
0	0	40	108	

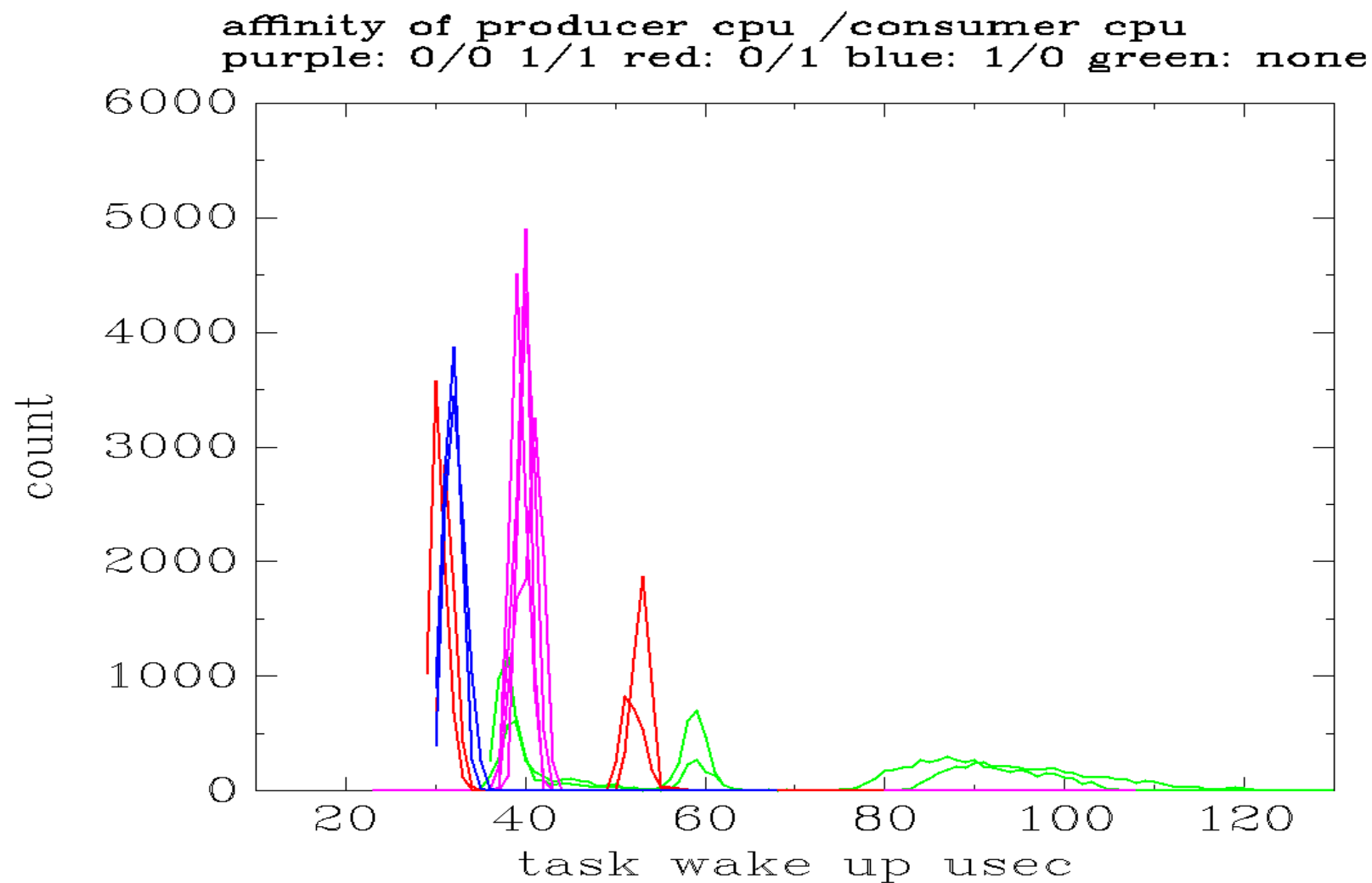
Fix Result (F1)

producer cpu affinity	consumer cpu affinity	task avg	switch max	usec
-----	-----	-----	-----	
x	x	69	147	baseline
x	x	68	159	baseline
0	0	39	64	
0	0	40	108	
1	1	40	94	
1	1	39	45	
0	1	40	66	
0	1	36	80	
1	0	31	68	
1	0	32	68	

Fix Result (F1)



Fix Result (F1)



Fix Conclusions (F1)

Processor migration increases task wake up time significantly.

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But setting processor affinity for a large number of real-time tasks is not a desired solution for the problem.

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Processor migration increases task wake up time significantly.

But setting processor affinity for a large number of real-time tasks is not a desired solution for the problem.

And task wake up time still larger than on 2.6.22.

Recall Tactic #1

Examine how the kernel source changed.

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Possible fix: revert to the old scheduler algorithm.

Recall Tactic #1

Examine how the kernel source changed.

The real-time scheduler became more aggressive about moving tasks between processors.

Possible fix: revert to the old scheduler algorithm.

But moving to older versions is not the direction that I want to go...

So attempt to improve the current version.

2.6.23 Real Time Scheduler

When a real time task wakes a higher priority real time task the real-time scheduler prefers to not push the (lower priority) currently running task to another processor.

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When a real time task wakes a higher priority real time task the real-time scheduler prefers to not push the (lower priority) currently running task to another processor.

The assumption is that the running process is cache hot and the newly awakened process is cache cold.

Revisit Test

P: producer thread, priority = 98

C: consumer thread, priority = 99

TI: timer interrupt handler

P [98]: set_current_state(TASK_UNINTERRUPTIBLE)

P [98]: wake_up_process(consumer)

C: [99]: consumer may preempt producer
or may be pushed to other processor

C: [99]: processes message

C: [99]: schedule()

P [98]: schedule_timeout()

TI [--]: timer irq, wake_up_process(producer)

P [98]: create next message

Fix (F2)

May allow consumer to remain on the same processor as the producer.

```
select_task_rq_rt()
```

```
+      /*  
+      * If current task on this CPU is about to sleep,  
+      * next task should run on this CPU.  
+      */  
+      if (current->state != TASK_RUNNING) {  
+          int cpu = smp_processor_id();  
+          if (cpu_isset(cpu, p->cpus_allowed))  
+              return cpu;  
+      }
```

Fix Result (F2)

producer cpu	consumer cpu	task wake up usec		
		-----		
		avg	max	
-----	-----	-----	-----	
x	x	69	147	baseline
x	x	68	159	baseline
0	0	39	64	Fix F1
0	0	40	108	Fix F1
1	1	40	94	Fix F1
1	1	39	45	Fix F1
x	x	23	63	Fix F2
x	x	23	65	Fix F2

Fix Result (F2)

producer and consumer always on same cpu,
instead of always on the other cpu

#		-- producer	-----
#	consumer	cpu 0	cpu 1
#	-----	-----	-----
#	cpu 0	5168	0
#	cpu 1	0	4832

Fix Result (F2)

producer and consumer always on same cpu,
instead of always on the other cpu

#		-- producer	-----
#	consumer	cpu 0	cpu 1
#	-----	-----	-----
#	cpu 0	5168	0
#	cpu 1	0	4832

How often does migration occur?

One migration per test run?

One migration per message?

Result (M2)

```
# producer cpu map:
```

#

[illegible]

#

```
# consumer cpu map:
```

#

[illegible]

Result (M2)

```
# producer cpu map:
```

#

```
# 0 0010101010000000000010011111111111111111
```

```
#      70  1111111111111111111111111111111111111111111111111
```

```
#      140  0000000000000011111111111111111111111111111111
```

#

```
# consumer cpu map:
```

#

```
# 0 0010101010000000000010011111111111111111
```

```
#      70  1111111111111111111111111111111111111111111111111
```

```
#      140  0000000000000011111111111111111111111111111111
```

Occasional migration, but producer and consumer always on same cpu

Revisit Test, in more detail

P: producer thread, priority = 98
C: consumer thread, priority = 99
TI: timer interrupt handler, irq context
TT: timer interrupt handler, thread context, priority = 50

P [98]: set_current_state(TASK_UNINTERRUPTIBLE)
P [98]: wake_up_process(consumer)
    C: [99]: consumer preempts producer
            producer may be pulled by other processor
    C: [99]: processes message
    C: [99]: schedule()
P [98]: schedule_timeout()
    TI [--]: timer irq
        TT [50]: wake_up_process(producer)
                producer may be pushed to other processor
P [98]: create next message

Revisit Test, in more detail

Possible double migration for producer.

P: producer thread, priority = 98
C: consumer thread, priority = 99
TI: timer interrupt handler, irq context
TT: timer interrupt handler, thread context, priority = 50

P [98]: set_current_state(TASK_UNINTERRUPTIBLE)
P [98]: wake_up_process(consumer)
    C: [99]: consumer preempts producer
            producer may be pulled by other processor
    C: [99]: processes message
    C: [99]: schedule()
P [98]: schedule_timeout()
    TI [--]: timer irq
        TT [50]: wake_up_process(producer)
                producer may be pushed to other processor
P [98]: create next message

Methodology (M3)

Verify double migration theory

Result (M3)

Adding further instrumentation to the producer task verified the suspected additional task migration.

Fix (F3)

Modify kernel/sched_rt.c algorithms to make real-time process migration less aggressive

Fix (F3)

Define “overloaded”, for purposes of pushing RT tasks, as:

number of tasks on RT run queue

$\geq$ CONFIG_RT_OVERLOAD

Fix (F3)

Define “overloaded”, for purposes of pushing RT tasks, as:

number of tasks on RT run queue
with priority > (MAX_USER_RT_PRIO / 2)

>= CONFIG_RT_OVERLOAD

Fix (F3)

Define “overloaded”, for purposes of pushing RT tasks, as:

number of tasks on RT run queue
with priority $> (\text{MAX\_USER\_RT\_PRIO} / 2)$

$\geq \text{CONFIG\_RT\_OVERLOAD}$

instead of

number of tasks on RT run queue > 0

Fix (F3)

Define “overloaded”, for purposes of pushing RT tasks, as:

number of tasks on RT run queue
with priority $> (\text{MAX\_USER\_RT\_PRIO} / 2)$

$\geq \text{CONFIG\_RT\_OVERLOAD}$

The priority of many kernel threads is:

$\text{MAX\_USER\_RT\_PRIO} / 2$

```
#define MAX_USER_RT_PRIO CONFIG_MAX_USER_RT_PRIO
```

```
MAX_USER_RT_PRIO / 2 == 50
```

PID	CMD	RTPRIO	CLS
3	[migration/0]	99	FF
4	[posix_cpu_timer]	99	FF
5	[softirq-high/0]	50	FF
6	[softirq-timer/0]	50	FF
7	[softirq-net-tx/]	50	FF
8	[softirq-net-rx/]	50	FF
9	[softirq-block/0]	50	FF
10	[softirq-tasklet]	50	FF
11	[softirq-sched/0]	50	FF
12	[softirq-rcu/0]	50	FF
13	[watchdog/0]	99	FF
27	[events/0]	1	FF
71	[krcupreemptd]	1	FF
94	[IRQ-125]	50	FF
103	[IRQ-152]	99	FF

Fix Result (F3)

producer cpu	consumer cpu	task wake up usec		
		-----		
		avg	max	
-----	-----	-----	-----	
x	x	69	147	baseline
x	x	68	159	baseline
x	x	23	63	Fix F2
x	x	23	65	Fix F2
x	x	23	33	2.6.22
x	x	21	41	Fix F3
x	x	21	25	Fix F3

Fix Result (F3)

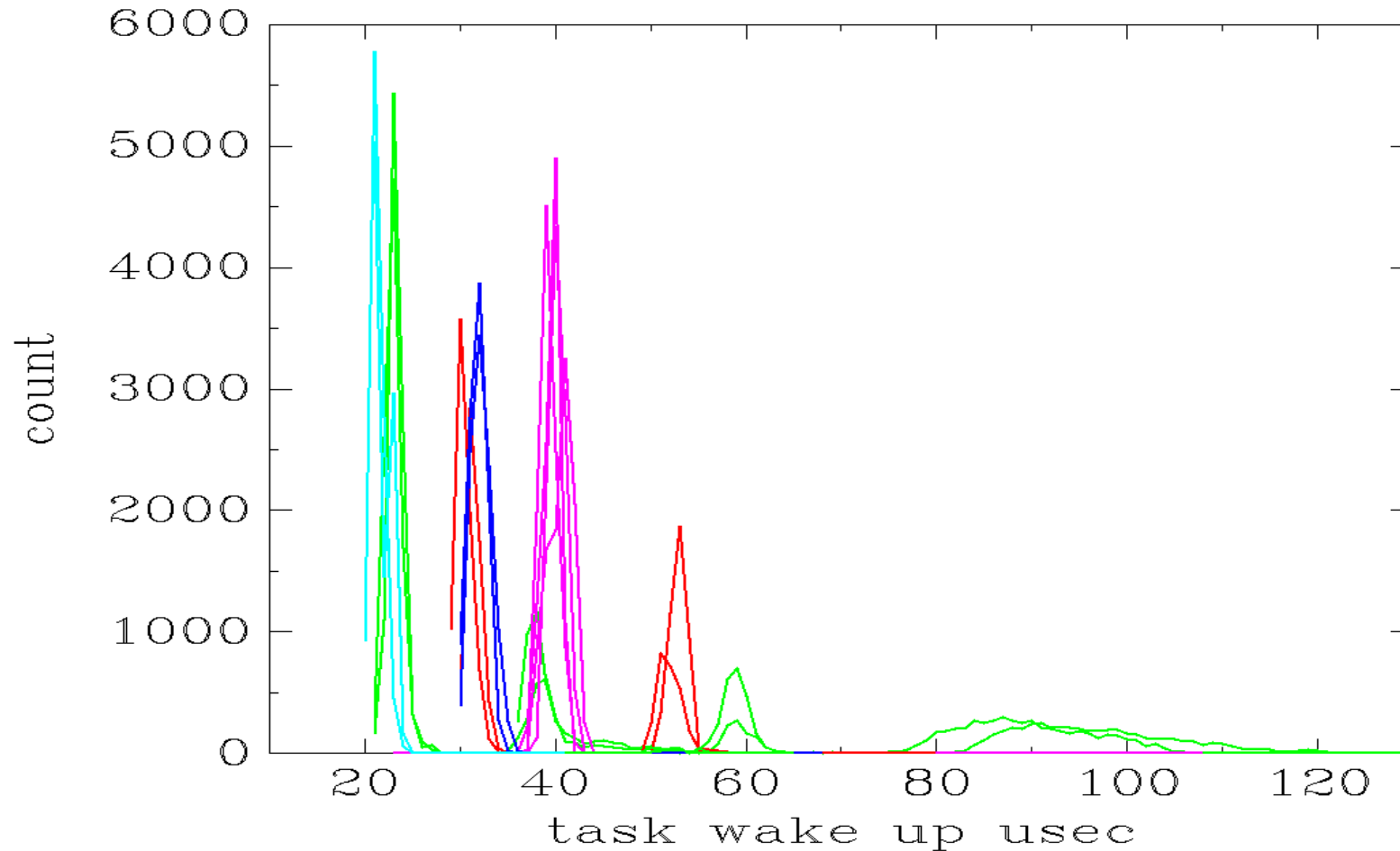
producer cpu	consumer cpu	task wake up usec		
		-----		
		avg	max	
-----	-----	-----	-----	
x	x	69	147	baseline
x	x	68	159	baseline
x	x	23	63	Fix F2
x	x	23	65	Fix F2
x	x	23	33	2.6.22
x	x	21	41	Fix F3
x	x	21	25	Fix F3

additional checks:

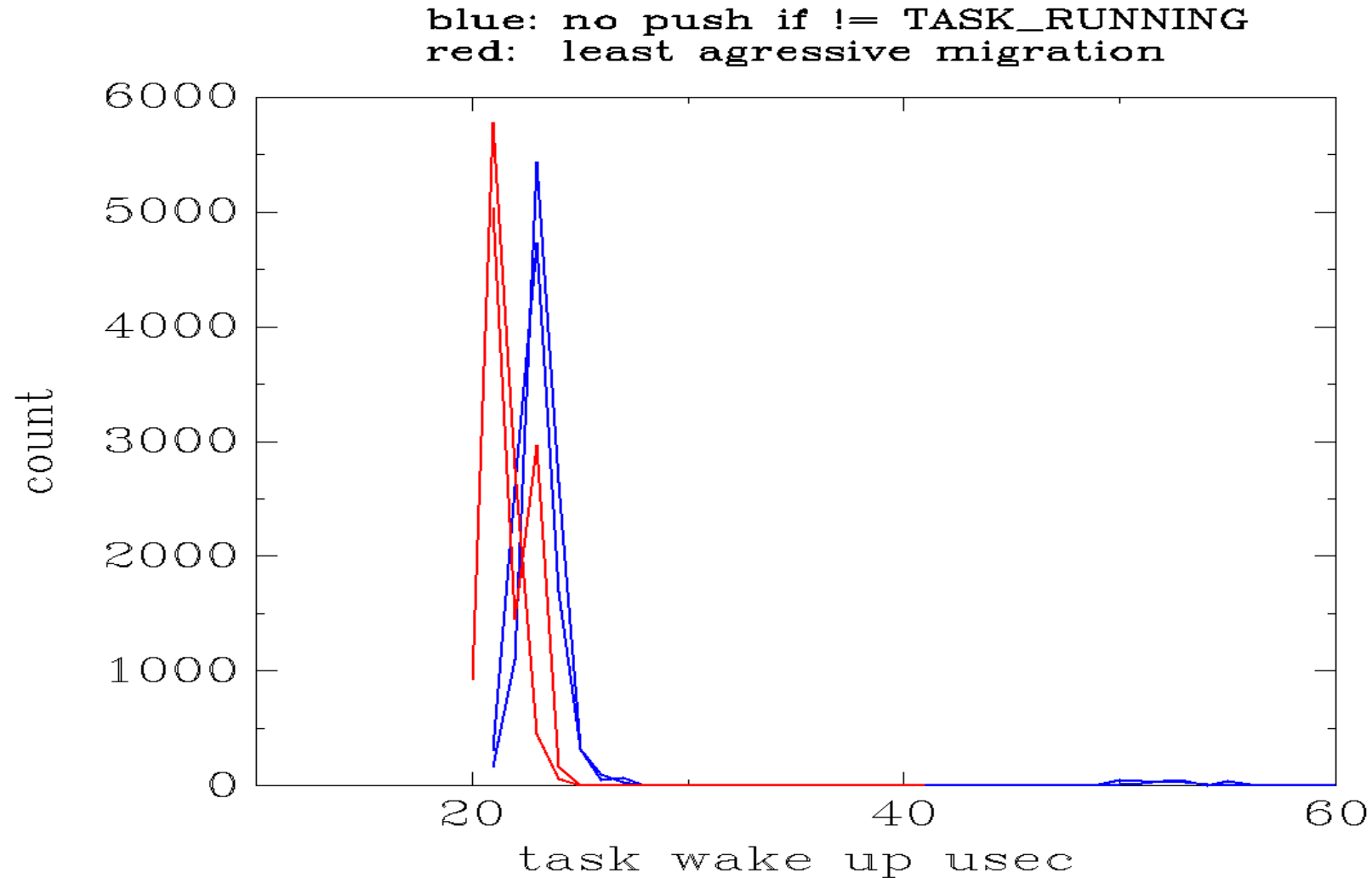
- average irq/preempt off improved
- maximum irq/preempt off improved
- cyclicttest results not negatively impacted

Fix Result (F2, F3)

affinity of producer cpu / consumer cpu
purple: 0/0 1/1 red: 0/1 blue: 1/0 cyan, green: low migration, none



Fix Result (F2, F3)



Fix Conclusion (F2, F3)

Reducing processor migration may decrease task wake up time significantly.

Fix Conclusion (F2, F3)

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But test is a rather simplistic case

real-time task processing time $\ll$ task switch time

real-time task processing time $\ll$ task migration time

Fix Conclusion (F2, F3)

Reducing processor migration may decrease task wake up time significantly.

But test is a rather simplistic case

real-time task processing time $\ll$ task switch time

real-time task processing time $\ll$ task migration time

Will these improvements apply to a more complex real-time application?

Strategy: Trust Nothing,
Blame Everything

Strategy: Trust Nothing, Blame Everything

A minor distraction from both the debug / fix process and the flow of this presentation. But this is about the point in the debug process that I got around to tracking an irritant in the data.

Strategy: Trust Nothing, Blame Everything

A minor distraction from both the debug / fix process and the flow of this presentation. But this is about the point in the debug process that I got around to tracking an irritant in the data.

Real life is never the clean, straight line process that this talk pretends to show.

Data from step $n + X$ is often hard to compare to data from step n .

Strategy: Trust Nothing, Blame Everything

A single very large maximum task wake up time was occasionally appearing during the early stages of the testing and improvements described in the previous slides.

The data for the tables of results and graphs shown on previous slides was recreated after resolving the cause of the large maximum.

Strategy: Trust Nothing, Blame Everything

A single very large maximum task wake up time was occasionally appearing during the early stages of the testing and improvements described in the previous slides.

CAUSE: a `printk()` in the consumer task, located before the test loop

Tactics

#1 Compare kernel config options

Still have not applied tactic #1 to the task wake up time issue.

Fix (F4)

1) Kernel configuration changes

`CONFIG_PREEMPT_RCU_BOOST=n`
`CONFIG_NO_HZ=n`

2) Disable ARM option to enable interrupts in `context_switch()`.

`CONFIG_DISABLE_WANT_INTERRUPTS_ON_CTXSW=y`

(Interrupts are enabled then disabled in `context_switch()` if `__ARCH_WANT_INTERRUPTS_ON_CTXSW` is defined. This is similar to, but somewhat different than, the experiment of enabling irqs on the return from interrupts path described in “Adventures in Real-Time Performance Tuning, Part 1”.)

Fix (F4)

1) Kernel configuration changes

`CONFIG_PREEMPT_RCU_BOOST=n`
`CONFIG_NO_HZ=n`

2) Disable ARM option to enable interrupts in `context_switch()`.

`CONFIG_DISABLE_WANT_INTERRUPTS_ON_CTXSW`

(Interrupts are enabled then disabled in `context_switch()` if `__ARCH_WANT_INTERRUPTS_ON_CTXSW` is defined. This is similar to, but somewhat different than, the experiment of enabling irqs on the return from interrupts path described in “Adventures in Real-Time Performance Tuning, Part 1”.)

Goal: verify that the config changes to reduce irq off time do not increase task wake up time

Fix Result (F4)

Average task wake up time,
10000 iteration test run 8 times per configuration

21	-	22 usec	CONFIG_DISABLE_WANT_INTERRUPTS_ON_CTXSW=y CONFIG_PREEMPT_RCU_BOOST=n CONFIG_NO_HZ=n
20	-	22 usec	CONFIG_DISABLE_WANT_INTERRUPTS_ON_CTXSW=y
21	-	24 usec	4 migration fixes, after merging unrelated patches
		22 usec	4 migration fixes, before merging unrelated patches
23	-	24 usec	2 migration fixes
40	-	43 usec	pinned to same processor
32	-	53 usec	pinned to different processor
		73 usec	no processor affinity

Not a large impact on average task wakeup time,
but a large improvement in irq/preempt off metric

A Bigger Picture Of Metrics (but still a subset of what I track)

AKA keeping the big picture in view

test num	cyclicttest						irq off						preempt off						irq/preempt off						---
	-----maximum----			----average----			-----maximum----			----average----			-----maximum----			----average----			-----maximum----			----average----			
	min	avg	max	min	avg	max	min	avg	max	min	avg	max	min	avg	max	min	avg	max	min	avg	max	min	avg	max	
00050	53	110	409	49	85	281	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	fix 3	
00051	56	160	401	49	86	272	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	fix 3	
00052	147	330	618	90	195	460	3	21	499	3	17	356	3	16	364	3	12	326	6	23	543	6	20	352	fix 3
00053	102	306	793	87	189	479	3	19	488	3	17	329	3	15	395	3	12	296	6	23	443	6	20	357	fix 3
00054	49	164	364	46	90	247	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	fix 3 + _CTXSW=y	
00055	53	185	391	47	95	268	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	fix 3 + _CTXSW=y	
00056	131	289	591	86	179	429	3	24	374	3	20	297	3	14	325	3	11	269	6	21	539	6	19	345	fix 3 + _CTXSW=y
00057	96	258	687	80	172	463	3	23	320	3	21	305	3	14	295	3	11	240	6	22	336	6	19	290	fix 3 + _CTXSW=y
00058	88	188	335	47	78	241	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	fix 4	
00059	49	111	314	45	72	240	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	fix 4	
00060	96	229	527	83	157	394	3	20	348	3	18	321	3	14	293	2	11	250	6	21	419	6	18	327	fix 4
00061	115	242	791	84	165	459	3	20	444	3	18	327	3	14	345	1	11	265	6	21	413	6	18	344	fix 4
00062	110	268	707	84	166	443	3	21	383	3	18	334	3	14	357	2	11	284	6	22	361	6	18	327	fix 4

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Keep real time application performance in sight while tuning individual components

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Watch a vast range of metrics and behaviors for each change

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Watch a vast range of metrics and behaviors for each change

Look at a large number of statistics for the metrics (for example, minimum, maximum, average, standard deviation)

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Keep real time application performance in sight while tuning individual components

Watch a vast range of metrics and behaviors for each change

Look at a large number of statistics for the metrics (for example, minimum, maximum, average, standard deviation)

Look at graphic representations of metrics

What Does It All Mean?

What is in the scope of a tuning effort?

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EVERYTHING, just like in any debugging effort!

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EVERYTHING, just like in any debugging effort!

- Instrumentation
- Tests
- Kernel
- Drivers
- Real Time Applications
- Other Applications
- External Influences

What Does It All Mean?

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You will need to write a new tool or leverage an existing tool.

Resources

Rtiwiki

http://rt.wiki.kernel.org/index.php/Main_Page

rt-user-list

<http://dir.gmane.org/gmane.linux.rt.user>

eLinux.org

http://elinux.org/Real_Time

cyclictest

<http://git.kernel.org/?p=linux/kernel/git/tglx/rt-tests.git;a=summary>

Resources

ftrace

<http://people.redhat.com/srostedt/ftrace-tutorial.odp>

kernel source: Documentation/ftrace.txt

hackbench

<http://devresources.linux-foundation.org/craiger/hackbench/>

LatencyTOP

<http://www.latencytop.org>

“Stress actions - things that will kill realtime performance”
and information about test programs and testing

http://elinux.org/Realtime_Testing_Best_Practices

Resources

A realtime preemption overview

<http://lwn.net/Articles/146861>

What's in the realtime tree

<http://lwn.net/Articles/252716>

Ninth Real-Time Linux Workshop 2007

<http://lwn.net/Articles/260118>

<http://linuxdevices.com/articles/AT4991083271.html>